

# GoCV/openCV

**An application of Go**

# Admin

- 
- Lets look at the news

# Open CV

- OpenCV
  - Is a c++ (with some C) library for doing real time computer vision.
  - Runs on all major platforms
    - Linux,
    - Windows (with a lot of work),
    - MacOS (except maybe apple silicon)
    - Android
  - Need gcc/g++
    - Minggw for you windows users without WSL

# OpenCV

- OpenCV is 20+ years old
  - First released in 2000.
  - So very mature, and provides lots of functionality
    - So we can't possibly cover it all
- wrappers/interface in many programming languages.
  - Python, java, Matlab, javascript
  - And of course GO!!

# GoCV

- GoCV is the go wrapper around goCV
  - <https://gocv.io/>
  - Its a bit of a bear to make, which is why I asked you to do it over the week.

# Simple Tutorial

- Lets dig through the first tutorial

```
import (  
    "gocv.io/x/gocv"  
)  
  
func main() {  
    webcam, _ := gocv.VideoCaptureDevice(0)  
    window := gocv.NewWindow("Hello")  
    img := gocv.NewMat()  
  
    for {  
        webcam.Read(&img)  
        window.IMShow(img)  
        window.WaitKey(1)  
    }  
}
```

# VideoCapture

- First
- `gocv.VideoCaptureDevice`
  - Open the camera and get ready to stream
  - Second return val is error if it fails to open the camera

# The window

- Easiest way to see the results is to use the gocv window
- `gocv.NewWindow(<name>)`
- Two params,
  - First is name, if there is already a window with this name, then it won't open a second
  - Second param is flags
  - Only default flag is autoresize
    - First window pops up small. Close it and window reopens correct size



# Bit Flags

- How many of you have used bit flags before?
  - ?

# Bit Flags

- How many of you have used bit flags before?
  - ?
  - Based on our experiences this semester I'll guess about 20% of you
    - Common in lower level CE/embedded programming where efficiency is very important.
- lets take a quick diversion and come back to bit flags

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- What is the biggest expense today in computer programs?
  - Programmer time
- What was the biggest expense 40+ years ago?
  - Maybe even 25-30 years ago
  - Computing equipment
  - What and why of the “y2k” issue

# Developers vs Programs

- So today you can get a linode  
<https://www.linode.com/pricing/> for \$5/month at the low end
- While a go developer is often making \$100k or more in the US
  - <https://www.indeed.com/salaries/golang-developer-Salaries>
  -

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  - And what do developers spend the most time on in any sort of “real” software?
    - Lucky volunteer again?
  - Reading the existing code to understand where and what changes to make

# Go philosophy

- The Go language is built for enterprise development
  - Google heritage of course
  - Small set of keywords
  - Slow pace of changes and major features
    - Good go code from 5 years ago still very readable today.
    - Java from 5 years ago?
    - Even python?
  - So go long emphasis on readability
    - Gofmt helps

# Optimize for what?

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# Optimize for what?

- So when do we not want to optimize for developer time (readability)?
  - Those rare cases where performance is critical and worth the extra development time
    - Real time systems (rockets, autonomous robots, self-driving cars)
    - Anything else which continuous performance needs
      - Deep internals of an operating system
      - graphics/game loop
      - Highly optimized libraries used by developers whose internals most people will not see.

# And now back....

- And now back to our regularly scheduled topic
  - So opencv and the Qt window library fall into some of those highly optimized back end libraries
  - QT runs the Tesla in-car GUI and other places with limited compute.
  - So they use optimizations that might be overkill elsewhere

# Bitflags

- In much of our computing
  - Boolean flags
  - In c++ and go booleans are 1 byte
    - In python and java even more
  - Not too much for 8 gigs of RAM
  - But if you need 16 flags and open hundreds of windows – can be a lot
    - What is a window discussion

# Bitflags II

- So solution use a byte or int16 to store a bunch of values each is a power of two
- Example from open cv cpp headers
  - `enum cv::MouseEventFlags {`
  - `cv::EVENT_FLAG_LBUTTON = 1,`
  - `cv::EVENT_FLAG_RBUTTON = 2,`
  - `cv::EVENT_FLAG_MBUTTON = 4,`
  - `cv::EVENT_FLAG_CTRLKEY = 8,`
  - `cv::EVENT_FLAG_SHIFTKEY = 16,`
  - `cv::EVENT_FLAG_ALTKEY = 32`
  - `}`



# Bitflags III

- Use bitwise or to use two flags together
  - `flags := EVENT_FLAG_RBUTTON | EVENT_FLAG_CTRLKEY`
- Then use bitwise and to check to see if a flag is set
  - `if flags & EVENT_FLAG_RBUTTON {`
    - This code only reached if the `EVENT_FLAG_RBUTTON` value was set in the flag
  - `flags :` `00001010`
  - `EVENT_FLAG_RBUTTON` `00000010`
  -



# Remember that program

- Lets dig through the first tutorial

```
import (  
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func main() {  
    webcam, _ := gocv.VideoCaptureDevice(0)  
    window := gocv.NewWindow("Hello")  
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    for {  
        webcam.Read(&img)  
        window.IMShow(img)  
        window.WaitKey(1)  
    }  
}
```

# Mat

- `img := gocv.NewMat()`
- Creates a new material 'Mat'
  - With zero value
- From docs: "Mat represents an n-dimensional dense numerical single-channel or multi-channel array.  
<and more>"
  - So this is going to be our image

# Get this frame

- Get the current frame

webcam.`Read`(&img)

- Pass pointer to a material which gets filled
- Return value is boolean – false if can't read

# Show the image

- Now we show the image on the window  
`window.IMShow(img)`
- Needs `WaitKey` next or will not show
- `WaitKey` takes param: minimum number of milliseconds to wait
- `WaitKey` also polls events – so event processing happens here

# Face Finder

- New lets try a face finder demo
- Before we can find faces need to get a classifier
  - <https://github.com/opencv/opencv/tree/master/data>
  - Basically a trained neural net in xml format
  - haarcascade\_frontalface\_default.xml
    - Large, but seems to work for wide variety of faces
    - Grab it from github

# The new main

```
func main() {  
  
    webcam, err := gocv.VideoCaptureDevice(0) //or 1  
  
    if err != nil {  
  
        fmt.Println(err)  
  
        return  
    }  
  
    defer webcam.Close()  
  
    displayWindow := gocv.NewWindow("Find a face")  
  
    classifier := gocv.NewCascadeClassifier()  
  
    success := classifier.Load("haarcascade_frontalface_default.xml")  
  
    if !success {  
  
        log.Fatal("Failed to load classifier - can't continue")  
  
    }  
  
    defer classifier.Close()  
  
    FindFaces(webcam, displayWindow, classifier)  
  
}
```

# Face Finder

- Lets build it
- Note the false positives
- On the mac in my office I'm 'superman' it can't find me with glasses – but without finds me fine



```
func FindFaces(camera *gocv.VideoCapture, window *gocv.Window, faceFiindingNet gocv.CascadeClassifier) {
```

```
img := gocv.NewMat()
```

```
defer img.Close()
```

```
for {
```

```
if ok := camera.Read(&img); !ok {
```

```
fmt.Printf("cannot read from camera!")
```

```
continue
```

```
}
```

```
if img.Empty() {
```

```
continue
```

```
}
```

```
potentialFaces := faceFiindingNet.DetectMultiScale(img)
```

```
for _, rectangle := range potentialFaces {
```

```
gocv.Rectangle(&img, rectangle, colornames.Darkkhaki, 3)
```

```
}
```

```
window.IMShow(img)
```

```
if window.WaitKey(10) >= 0 {
```

```
break
```

```
}
```



# Now lets extend that

- Lets extend the face finder to do a privacy blur
  - Lets try that now

# Now lets extend that

- Lets extend the face finder to do a privacy blur
  - Lets try that now
  - `faceRegion := img.Region(rectangle)`
  - `gocv.GaussianBlur(faceRegion, &faceRegion, image.Pt(55, 95), 0, 0, gocv.BorderDefault)`
  - `faceRegion.Close()`

# Now lets extend that

- Lets extend the face finder to do a privacy blur
  - Lets try that now
- One more if we have time
  - Lets write “redacted” over the blur

