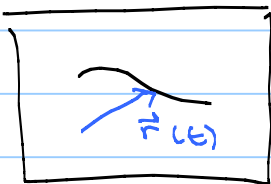


Lecture 5 - Math 2: Vectors + Coordinate Transformations

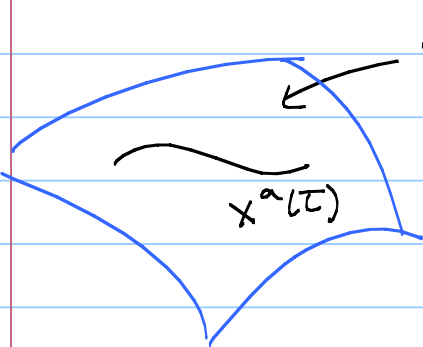
Note Title

1/29/2006

Math you know: Let $\vec{r}(t)$ describe the position of a particle at all times - it describes a curve in our manifold.



The velocity $\vec{v} = \frac{d\vec{r}}{dt}$ is tangent to the curve.



$v^a = \frac{dx^a}{dt}$ ← tangent vector to a curve

Notice that the index placement is naturally upstairs.

⇒ We usually write $\vec{v} = v_x \hat{x} + v_y \hat{y} + v_z \hat{z}$

$\hat{x}, \hat{y}, \hat{z}$ are basis vectors

Now $v^a = (v^1, v^2, v^3)$ are components in the $(\hat{x}, \hat{y}, \hat{z})$ basis

Rename basis vectors:

$$\left. \begin{aligned} \vec{e}_x &= \hat{x} \\ \vec{e}_y &= \hat{y} \\ \vec{e}_z &= \hat{z} \end{aligned} \right\}$$

call \vec{e}_μ the collection of basis vectors

Suppose we have a vector \vec{v} w/ components v^a in the $(\vec{e}_x, \vec{e}_y, \vec{e}_z) = \vec{e}_a$ basis.

How do the components of \vec{v} change if we change coordinates?

Einstein summation convention. $\vec{v} = v^1 \vec{e}_1 + v^2 \vec{e}_2 + v^3 \vec{e}_3 = \sum_a v^a \vec{e}_a = v^a \vec{e}_a$

repeated indices means sum.

In new coordinates, the same vector \vec{v} has new components and new basis vectors.

$$\vec{v} = v^a \vec{e}_a = v'^{\mu} \vec{e}'_{\mu}$$

How are v^a related to v'^{μ} and \vec{e}_a related to \vec{e}'_{μ} ?

Take an easy example: 2-dim plane: coord (x, y) & (r, θ)

$$x = r \cos \theta$$

$$r = \sqrt{x^2 + y^2}$$

$$\vec{e}_1 = \vec{e}_x = (1, 0)$$

$$y = r \sin \theta$$

$$\theta = \arctan(y/x)$$

$$\vec{e}_2 = \vec{e}_y = (0, 1)$$

? How is \vec{e}_x defined? Let $\vec{r} = x\vec{e}_x + y\vec{e}_y = x^a\vec{e}_a$

$$\vec{e}_x = \frac{\partial \vec{r}}{\partial x} \implies \boxed{\vec{e}_a = \frac{\partial \vec{r}}{\partial x^a}}$$

now $\vec{r} = x\vec{e}_x + y\vec{e}_y = r \cos \theta \vec{e}_x + r \sin \theta \vec{e}_y$

Then $\vec{e}_{r,\theta} = \frac{\partial \vec{r}}{\partial r} = \cos \theta \vec{e}_x + \sin \theta \vec{e}_y$
 $\vec{e}_{\theta} = \frac{\partial \vec{r}}{\partial \theta} = -r \sin \theta \vec{e}_x + r \cos \theta \vec{e}_y$

These are the basis vectors in (r, θ) coord.

Note: The new basis vectors are orthogonal, but they are not normalized.

What did we just do? Call (x, y) the x^a coord and (r, θ) the x'^a coordinates.

We took $\vec{r}(x^a) = x\vec{e}_x + y\vec{e}_y$ + said $\vec{e}'_a = \frac{\partial \vec{r}(x^a)}{\partial x'^a}$
New basis in x'^a

o but we had $x^a = x^a(x'^a)$, so $\vec{e}'_a = \frac{\partial \vec{r}}{\partial x^b} \frac{\partial x^b}{\partial x'^a}$

or $\boxed{\vec{e}'_a = \vec{e}_b \frac{\partial x^b}{\partial x'^a}}$ ← How basis vectors transform.

$$\vec{e}'_a = \vec{e}_b \frac{\partial x^b}{\partial x'^a}$$

← write out:

$$\begin{aligned} \vec{e}'_x &= \vec{e}_x \frac{\partial x}{\partial x'} + \vec{e}_y \frac{\partial y}{\partial x'} = \cos\theta \vec{e}_x + \sin\theta \vec{e}_y \\ \vec{e}'_y &= \vec{e}_x \frac{\partial x}{\partial y'} + \vec{e}_y \frac{\partial y}{\partial y'} = -\sin\theta \vec{e}_x + \cos\theta \vec{e}_y \end{aligned}$$



same as above

$$\vec{e}'_a = \vec{e}_b \frac{\partial x^b}{\partial x'^a}$$

← General transformation law for basis vectors.

Now look at $\vec{v} = v^a \vec{e}_a = v'^a \vec{e}'_a$

Two representations of the same vector in terms of different bases.

$$v^a \vec{e}_a = v'^b \vec{e}'_b = v'^b \vec{e}_a \frac{\partial x^a}{\partial x'^b}$$

How must v'^b be related to v^a ?

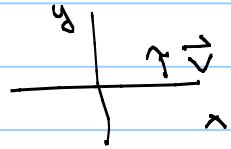
$$v^a \frac{\partial x'^b}{\partial x^a} = v'^b$$

Vector components transform opposite basis.

$$v'^b \vec{e}'_b = v^a \frac{\partial x'^b}{\partial x^a} \frac{\partial x^c}{\partial x'^b} \vec{e}_c = v^a \delta^c_a \vec{e}_c = v^a \vec{e}_a$$

A Kronecker delta func.

Example: Take a vector $(0, 1) = v^a$ in the (e_x, e_y) basis located at $\vec{r} = 1\vec{e}_x$



What is this vector in (r, θ) coordinates?

$$v^a = \frac{\partial x^a}{\partial x^b} v^b$$

$$v^r = \frac{\partial r}{\partial x}(0) + \frac{\partial r}{\partial y}(1) = \frac{y}{\sqrt{x^2+y^2}} = \frac{0}{\sqrt{1^2+0^2}} = 0.$$

$$v^\theta = \frac{\partial \theta}{\partial x}(0) + \frac{\partial \theta}{\partial y}(1) = \frac{\partial \arctan(y/x)}{\partial y} = \frac{1}{x^2+y^2} = 1$$

$$\vec{v} = \vec{e}_\theta \quad \text{at } \vec{r} = 1\vec{e}_x.$$