

We are just trying to solve for  $\vec{E}$ !

\* For static charge distributions

1.) Brute Force 
$$\vec{E}(\vec{r}) = \int_{\text{space}} \frac{\rho(\vec{r}') d\vec{r}'}{|\vec{r} - \vec{r}'|^2}$$

2.) Symm, Gauss's Law

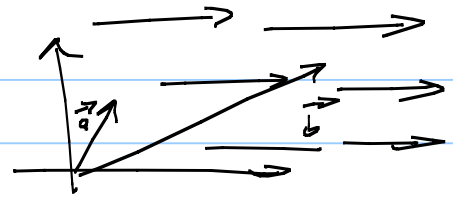
$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{\text{inside}}}{\epsilon_0}$$

Much of the trouble, especially brute force, is integrating over the vector  $\vec{r}$ , which is not constant.

So, can we be clever-er? yes

Electric - Potential  $V(\vec{r}) = \text{Scalar} = \frac{\text{energy}}{\text{charge}}$   
= volt

$\vec{V}$  = vector field



How to get there...

we know

$\int_{\vec{a}}^{\vec{b}} \vec{V} \cdot d\vec{l}$  = HUGELY depends on  
the path from  $\vec{a}$  to  $\vec{b}$   
strangely path dependant  
we saw this, pg 25.

However, is  $\vec{V} = -\vec{V}^T$   
Then

$$\int_{\vec{a}}^{\vec{b}} (\vec{V}^T) \cdot d\vec{l} = T(\vec{b}) - T(\vec{a})$$

$\vec{E}$   $\neq$  Path Depend

it is Fund Theorem of gradients  
just like Fund Theorem  
of calc

$$\int_{x_1}^{x_2} \left(\frac{df}{dx}\right) dx = f(x_2) - f(x_1)$$

Perhaps,  $\int_{\vec{a}}^{\vec{b}} \vec{E} \cdot d\vec{l}$  is path indep.

if so, then  $\vec{E}$  can be expressed

as gradient of some scalar

$$\vec{E} = -\nabla V \quad (*\text{note } V, \text{ not } \vec{V} = \text{vector field})$$

and since  $V = \text{Electric potential} = \text{scalar}$   
it may be EASIER to solve for

$V(r)$  & then later take  $-\vec{\nabla}V$  to get  $\vec{E}$

YES! That's idea. OK then

1<sup>st</sup> establish that

$$\int_{a \rightarrow b} \vec{E} \cdot d\vec{l} = \text{path independent}$$

1) either  $= V(\vec{b}) - V(\vec{a})$   
or 2)  $\oint \vec{E} \cdot d\vec{l} = 0$

will use Stokes theorem to help

$$\int_{a \rightarrow b} \vec{E} \cdot d\vec{l} = \int_A (\vec{\nabla} \times \vec{E}) \cdot d\vec{A}$$

ie

$$\vec{E} =$$

conservative

& discussion

is general

for all

conservative

forces: NOTE

All 4 forces ARE

conservative! Friction

counts this a bit

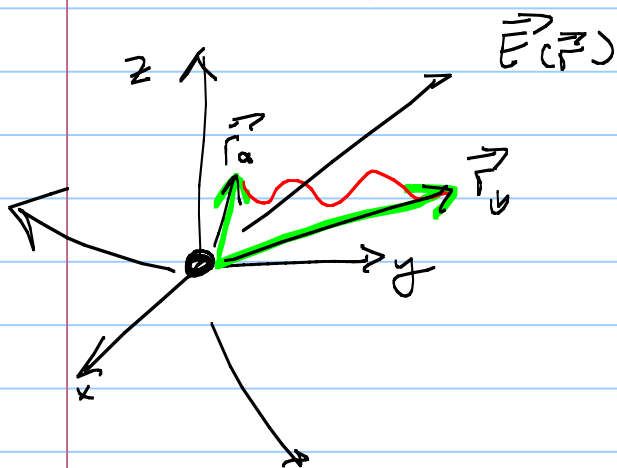
but definitely @ smallest

level, don't see it,

just conservative forces.

Consider (again, this development is top) static pt charge distributions ...

$$\vec{E} = k \frac{q}{r^2} \hat{r} \quad = \text{pt charge @ the origin}$$



consider

$$\int_{a \rightarrow b} \vec{E} \cdot d\vec{l} \Rightarrow \text{any coord system is legit, spherical is easiest}$$

$$d\vec{l} = dr \hat{r} + r d\sigma \hat{\sigma} + r \sin\sigma d\phi \hat{\phi}$$

$$\oint \vec{E} = E(r) \hat{r}$$

$$\int_{a \rightarrow b} E(r) \hat{r} \cdot (dr \hat{r} + r d\sigma \hat{\sigma} + r \sin\sigma d\phi \hat{\phi})$$

$$= \int_a^b E(r) dr = \int_a^b k \frac{q}{r^2} dr = -k \frac{q}{r} \left[ \frac{1}{r_b} - \frac{1}{r_a} \right]$$

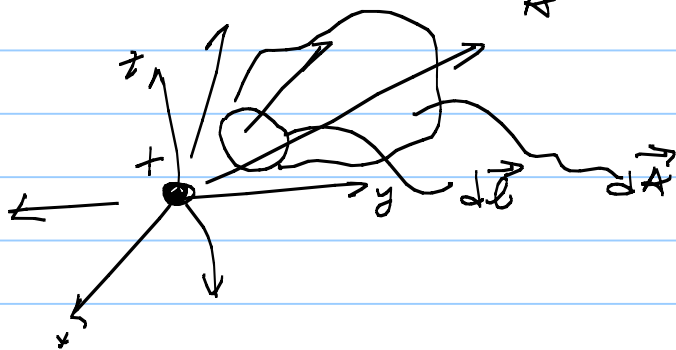
now is this path dependent?

No! doesn't depend on  $\sigma$ , or  $\phi$  and clearly only depends on endpoints

Clearly  $\int_{r_0}^{r_2} \vec{E}(\text{point charge}) \cdot d\vec{r} = -k\frac{q}{r} \left[ \frac{1}{r_0} - \frac{1}{r_2} \right]$

$$\oint \vec{E}(\text{pt charge}) \cdot d\vec{r} = 0$$

$\therefore \oint \vec{E}(\text{pt charge}) \cdot d\vec{r} = \int_A (\vec{\nabla} \times \vec{E}(\text{pt charge})) \cdot d\vec{A} = 0$



New, clearly  $d\vec{r} \not\perp \vec{E} \neq 0$   
But also

$d\vec{A} \not\perp \vec{E} \neq 0$  AND Since

A = arbitrary — Anything and everything,

Then  $\vec{\nabla} \times \vec{E}(\text{pt charge}) = 0$

idea

$$\int_0^1 x dx = 3 \int_0^1 x^2 dx = 1$$

But clearly integrands are not  $\equiv$   
only way

$$\int (\text{integrand 1}) dx = \int (\text{integrand 2}) dx$$

is is you consider All limits

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Author's callout  
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so  $\int_{a \rightarrow b} \vec{E} \cdot d\vec{l} \neq \text{path dep}$  and  $\vec{\nabla} \times \vec{E} = 0$  } For not charge!

Clearly a "Bigger" net charge distribution

$\vec{E}$  field is built by vector superposition

$$\vec{E}_{\text{TOT}} = \vec{E}_1 + \vec{E}_2 + \dots$$

then  $\vec{\nabla} \times \vec{E}_{\text{TOT}} = \underbrace{\vec{\nabla} \times \vec{E}_1}_{=0} + \dots = 0$

Thus  $\int_{a \rightarrow b} \vec{E} \cdot d\vec{l} = \text{path indep}$  } For All Static Charge distributions

$\vec{\nabla} \times \vec{E} = 0$

This is key  
Because ↷

of course  
then  
 $\vec{E} = -\nabla V$



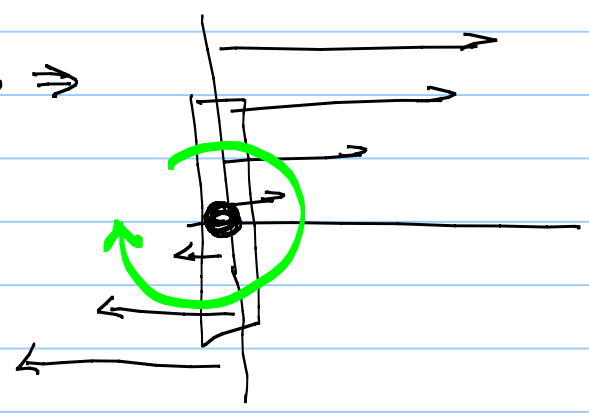
it says that  $\vec{E}$  (static charge distributions) are

IRROTATIONAL!

ie

non-zero curls  
 $\neq 0$  curls  $\Rightarrow$

$$\vec{V} = y \hat{x}$$



Could

Never ever be constructed by static charge distributions

$$\vec{\nabla} \times \vec{E} (\text{static-charge dist}) = 0$$

OK in Business for static charge distributions

Just got

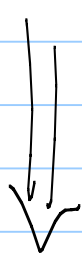
$$\int_{\vec{a}}^{\vec{b}} \vec{E} \cdot d\vec{\ell} \neq \phi(\text{path}) \quad \therefore \text{we know this is only true when vector field}$$

$$\int_{\vec{a}}^{\vec{b}} (\vec{\nabla} T) \cdot d\vec{\ell}$$


Diagram: A curved arrow points from the text 'only true when vector field' to the term  $(\vec{\nabla} T) \cdot d\vec{\ell}$  in the second equation.

But let see here

$$\int_{\vec{a}}^{\vec{b}} \left( \frac{\vec{F}}{\epsilon} \right) \cdot d\vec{\ell} \text{ looks a lot like definition of WORK}$$

Diagram: A circle is drawn around the  $\vec{F}$  in the numerator of the fraction in the equation above.

so lets define a  $\phi$  and

$$\frac{\text{work}}{\text{charge}} = \phi$$


⚡ since the path from  $\vec{a}$  to  $\vec{b}$  doesn't matter

⚡ work  $\Rightarrow$ 's between, from,  $\vec{a}$  to  $\vec{b}$ , we'd like to associate a potential at a pt instead of between two points

So we all agree on some  $\vec{c} = \vec{0}$  origin  
then

✓ for any  $\vec{r}$

$$V(\vec{r}) = - \int_0^{\vec{r}} \vec{E} \cdot d\vec{l} = \text{Electric potential}$$

$$\frac{E \cdot dr}{e} = \frac{\text{Energy}}{\text{Coulomb}} = \text{Volt}$$

so

$$V(\vec{b}) - V(\vec{a}) = - \int_0^{\vec{b}} \vec{E} \cdot d\vec{l} + \int_0^{\vec{a}} \vec{E} \cdot d\vec{l}$$

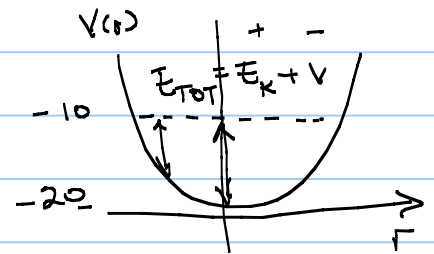
$$- \int_0^{\vec{b}} \vec{E} \cdot d\vec{l} - \int_0^{\vec{a}} \vec{E} \cdot d\vec{l}$$

$$V(\vec{b}) - V(\vec{a}) = - \int_{\vec{a}}^{\vec{b}} \vec{E} \cdot d\vec{l}$$

ie path indep  
But more formally

$$\int_{\vec{a}}^{\vec{b}} \nabla V \cdot d\vec{l} = - \int_{\vec{a}}^{\vec{b}} \vec{E} \cdot d\vec{l}$$

minus: convention  
For BOUND System!  $E_{TOT} = (-)$



$$E_K = E_{TOT} - V$$

$$-10 - (-20) =$$

For both sides,  $\vec{a} \rightarrow \vec{b}$  is completely path independent

again This is Key

$$\int_0^1 dx = 2 \int_0^1 x dx$$

But integrands  $\neq 0$

to be  $=$ , has to be true for all limits

we just showed

$$\int_{\vec{r}_0}^{\vec{r}_1} \vec{\nabla} V \cdot d\vec{\ell} = - \int_{\vec{r}_0}^{\vec{r}_1} \vec{E} \cdot d\vec{\ell}$$

for all  
limits  
& paths

$$\vec{E} = -\vec{\nabla} V$$

